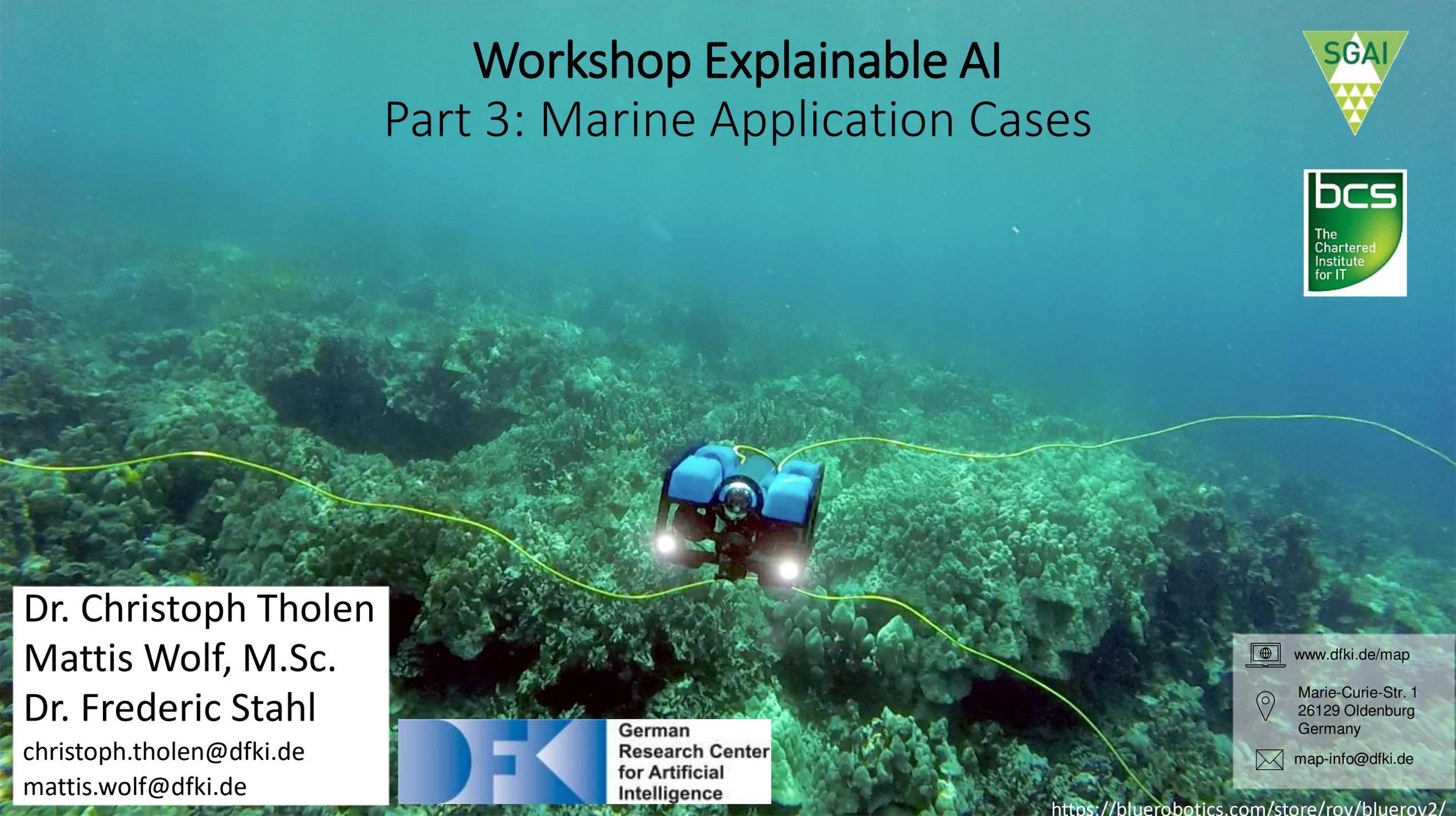


# Workshop Explainable AI

## Part 3: Marine Application Cases



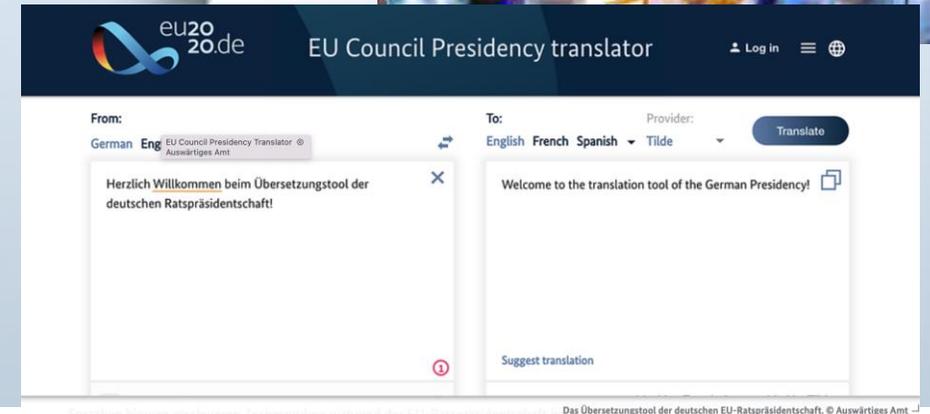
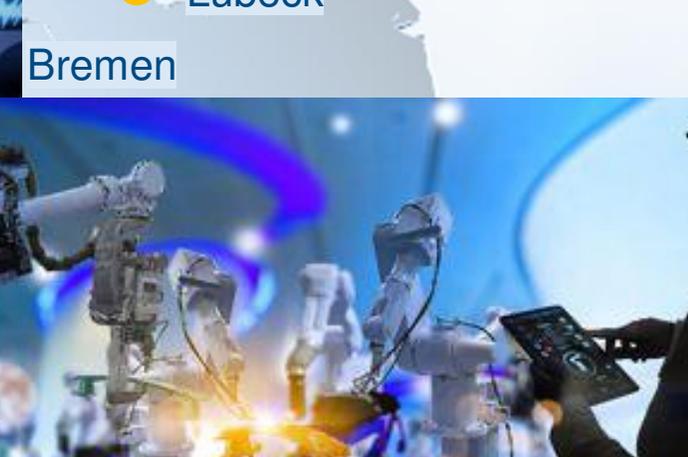
Dr. Christoph Tholen  
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Dr. Frederic Stahl  
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 [www.dfki.de/map](http://www.dfki.de/map)  
 Marie-Curie-Str. 1  
26129 Oldenburg  
Germany  
 [map-info@dfki.de](mailto:map-info@dfki.de)

<https://bluerobotics.com/store/rov/bluerov2/>

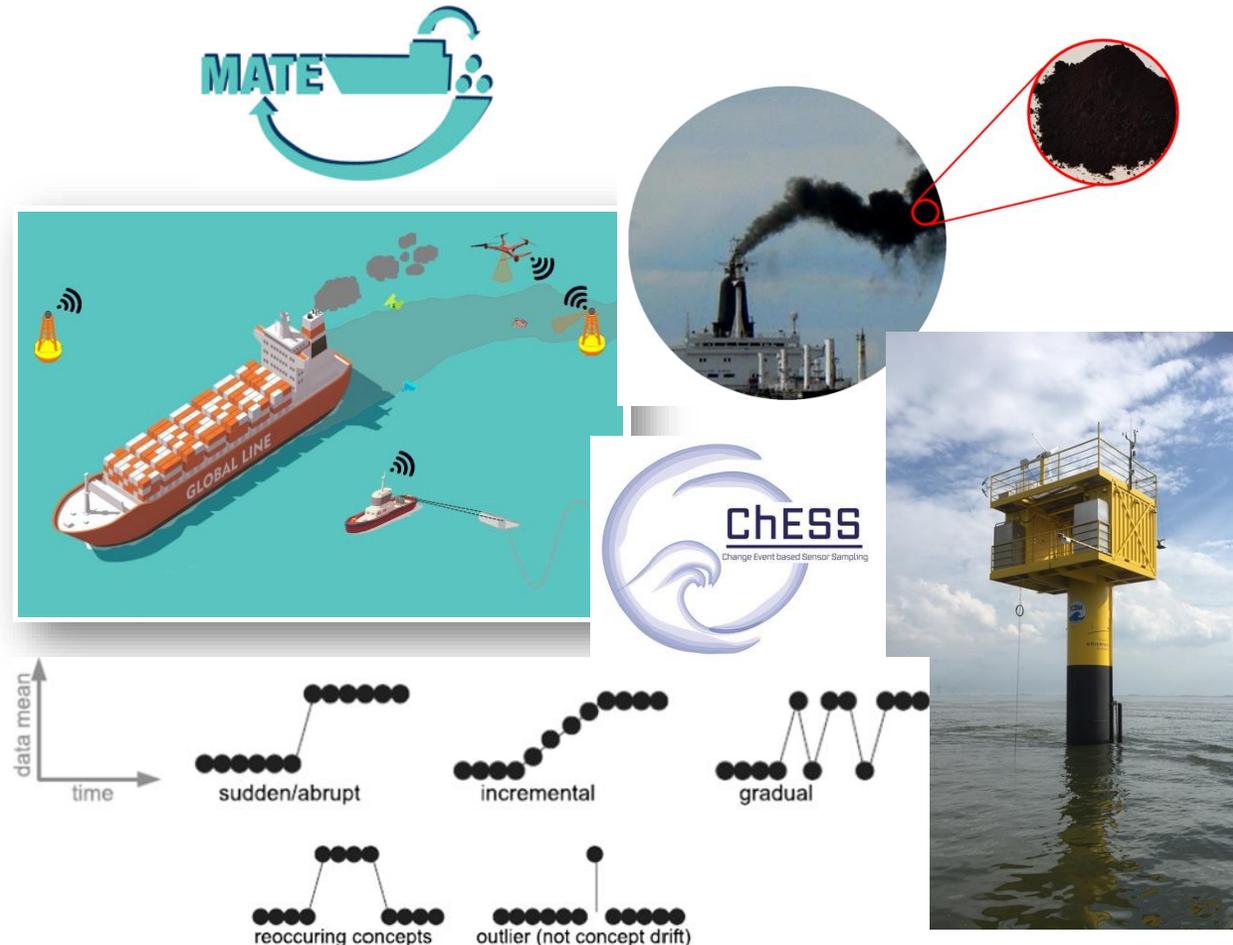
# DFKI – German Research Center for Artificial Intelligence



DFKI is one of the leading (applied) AI research centers

## Sensing is believing...

- Intelligent sensors and distributed systems for automatic perception and classification in the aquatic environment
  - Autonomous analysis of multisensory data using artificial intelligence methods, techniques and tools
  - Real-time data stream analysis and integration into a high-dimensional situation picture
- ➔ **We combine sensor technology and artificial intelligence to evaluate environmental situations and identify options for action**



# Why marine sciences?

Blue planet: oceans are the lungs of the planet.

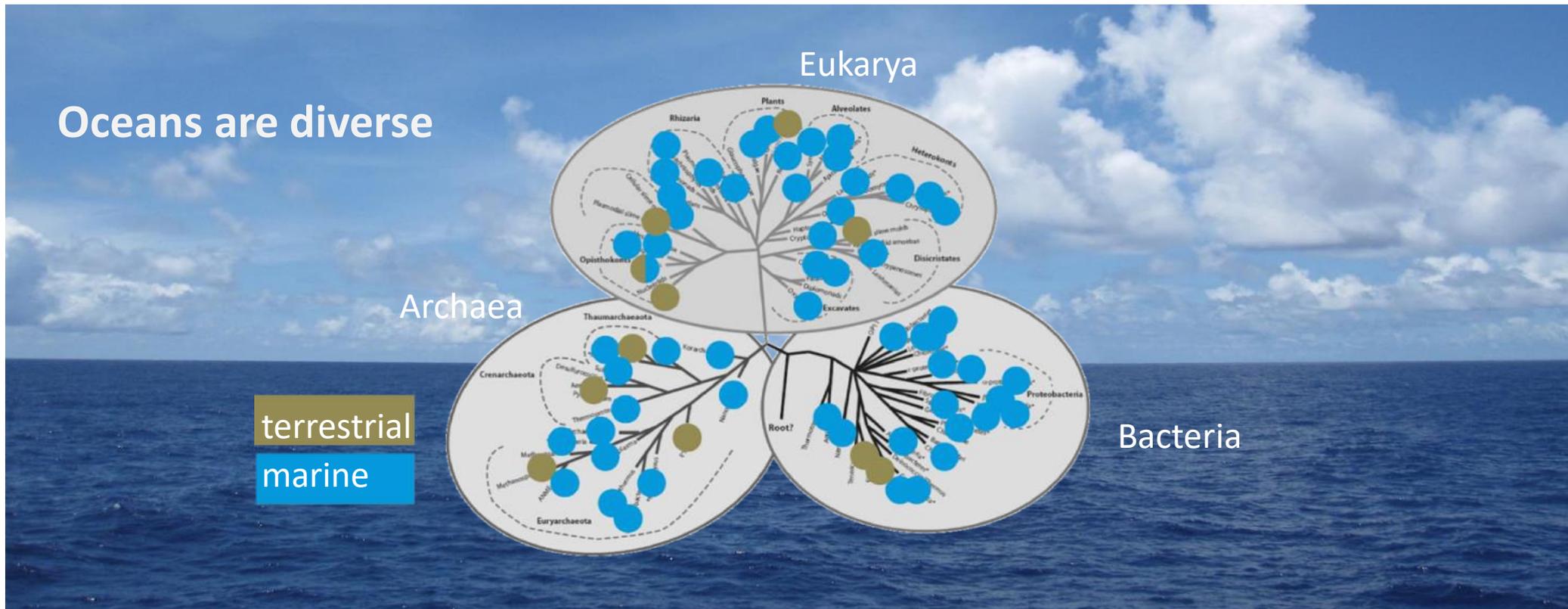
50% of the global oxygen production is produced by photosynthesis of marine algae.



# Why marine sciences?

Oceans are home to the world's largest diversity of species and habitats.

Annually 100 Mio tons of marine organisms are exploited as food source.



# Why marine sciences?

50% of the human population lives in coastal areas (< 100km).

Including 12 out of 16 mega cities (> 10 Mio. inhabitants).



# Why marine sciences?

Global warming is causing sea levels to rise. Pesticides and nutrients end up in coastal waters. Sewage discharge and litter runoff into the oceans. And many more...

**Oceans are at risk!**





iImagine



Marine Perception

Plastic waste and emission detection



Intelligent sensors and situational awareness

# DFKI MAP Projects

- Common in all past projects is a strong connection to different stakeholders from various different fields like
  - Local Governments
  - NGOs
  - UN
  - Etc.
- Often stakeholders questioned the outcome of the AI algorithms, especially if the results did not help their own agenda
- Here XAI methods can help to increase the trust of stakeholders

→ **XAI next natural step**



2021  
2030 United Nations Decade  
of Ocean Science  
for Sustainable Development



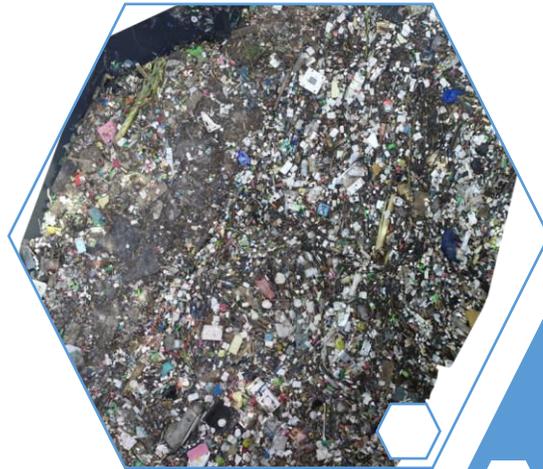
KEMENTERIAN KOORDINATOR  
BIDANG KEMARITIMAN  
DAN INVESTASI



WORLD BANK GROUP



# Agenda



Plastic  
waste  
detection

Assistance  
System for  
Nautical  
Officers



# Floating Litter Detection: Machine learning on drone image data

An aerial photograph showing a wide, shallow waterway or canal heavily littered with floating trash. The trash consists of numerous pieces of white and yellow plastic, along with other debris. The waterway is flanked by green grassy banks and residential buildings. A paved path runs alongside the water on the right, where a small red motorized vehicle is visible. The background shows a dense urban area with various buildings and structures.

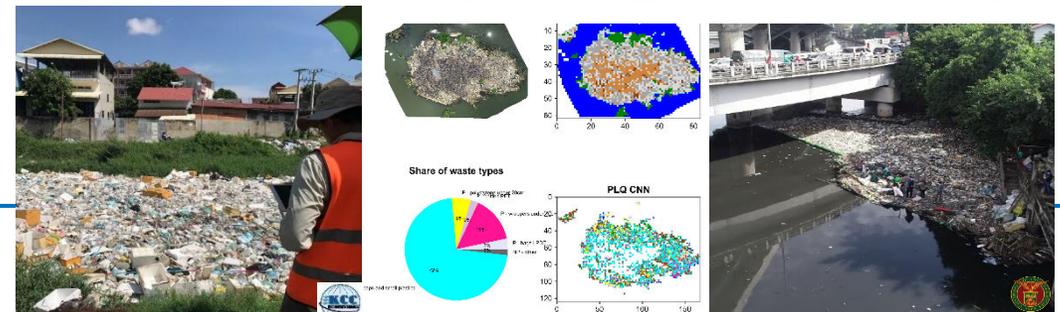
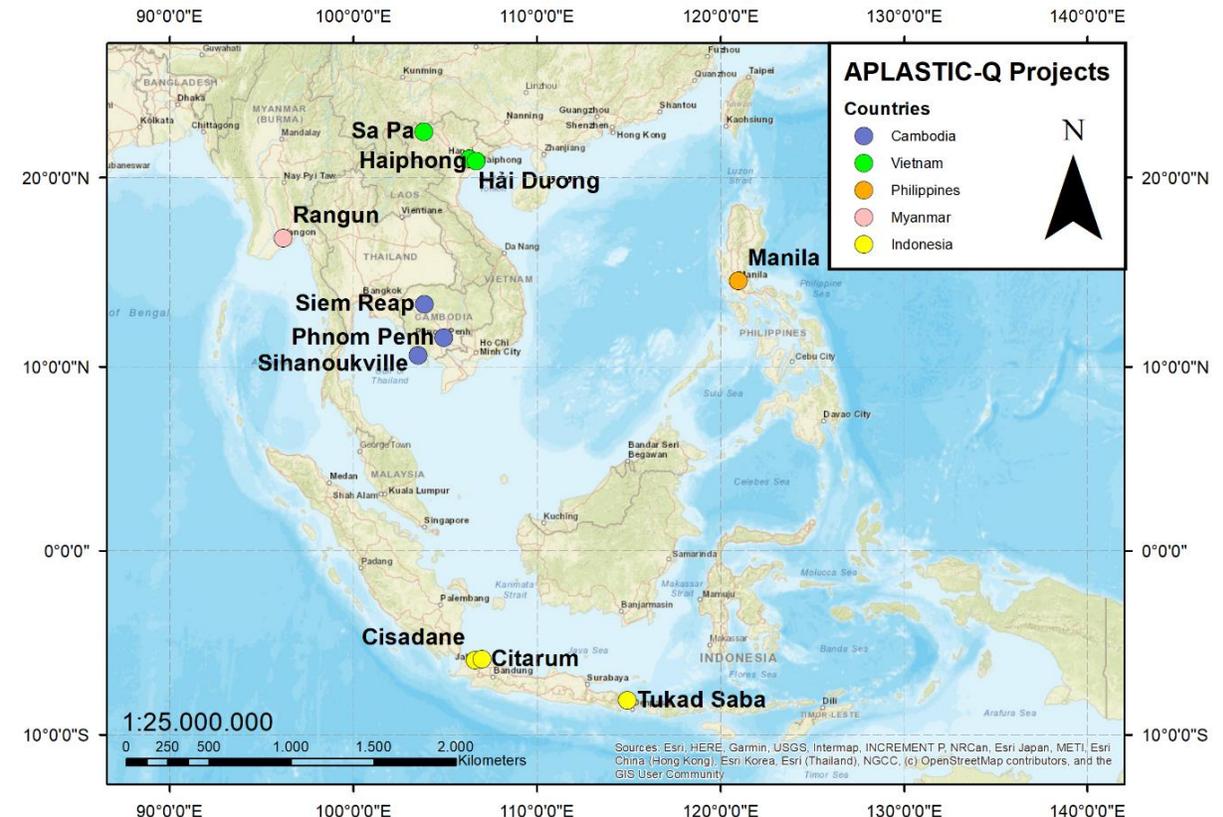


**Plastic Waste**  
A global problem that affects many aspects of human and natural life

# Plastic waste detection in ASEAN

## Conducted monitoring projects in five ASEAN countries

- Collaborated with local universities / companies
- Projects involved plastic waste assessment using:
  - Drone / action cam surveys with AI-based waste analysis**
  - Field surveys (net surveys)
  - Remote sensing via satellites
- Impact & Capacity Building: local, regional and national scope
- Focus on **easy-to-use methodologies** that enable assessment and monitoring



# AI-based waste monitoring example: Cisadane river mouth



## Level A:

High resolution imagery of river section

→ Identify waste hotspots

## Level B:

Very high resolution imagery for waste accumulations

→ Assess waste quantities & waste types

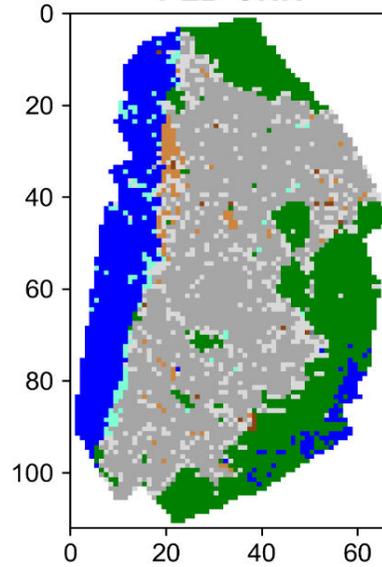


# Cisadane river mouth

Input image

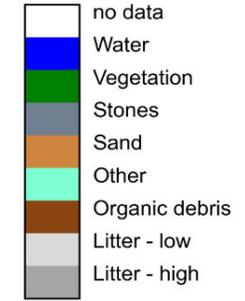


PLD CNN



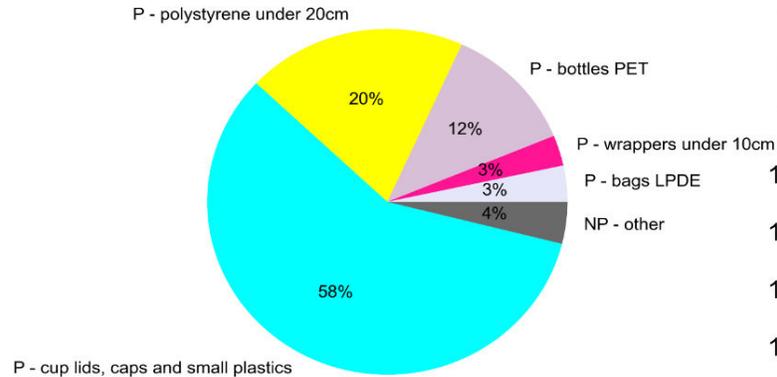
Assessed classifications, abundances, areas and volumes

Litter - high	2257
Litter - low	601
Organic debris	22
Other	104
Sand	102
Stones	2
Vegetation	1266
Water	868
Litter abundance	12487
Litter m <sup>2</sup>	167
Litter m <sup>3</sup>	47
Org. Debris m <sup>2</sup>	1
Org. Debris m <sup>3</sup>	0

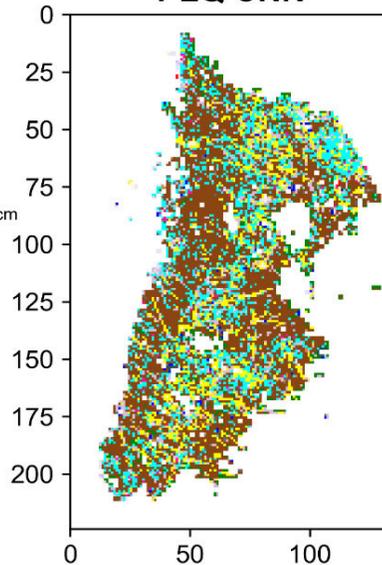


Waste quantities

Share of waste types



PLQ CNN



Altitude corrected assessed areas and pollution type abundances

	Classifications	Assessed abundances
P - bags LPDE thick	2	1
P - bags LPDE	256	256
P - bags robust PET	0	0
P - wrappers under 10cm	108	216
P - wrappers over 10cm	8	8
P - bottles PET	908	908
P - polystyrene under 20cm	1497	1497
P - polystyrene over 20cm	97	29
P - PPCP bottle	0	0
P - PPCP medical waste	0	0
P - PPCP other	0	0
P - fishing gear	0	0
P - cup lids, caps and small plastics	2202	4404
P - other plastics over 20cm	29	20
NP - rubber	0	0
NP - metal	0	0
NP - glass	0	0
NP - other	296	296
NW - sand	75	0
NW - vegetation	442	0
NW - wood	5415	0
NW - water	76	0
NW - other	21	0



Waste types

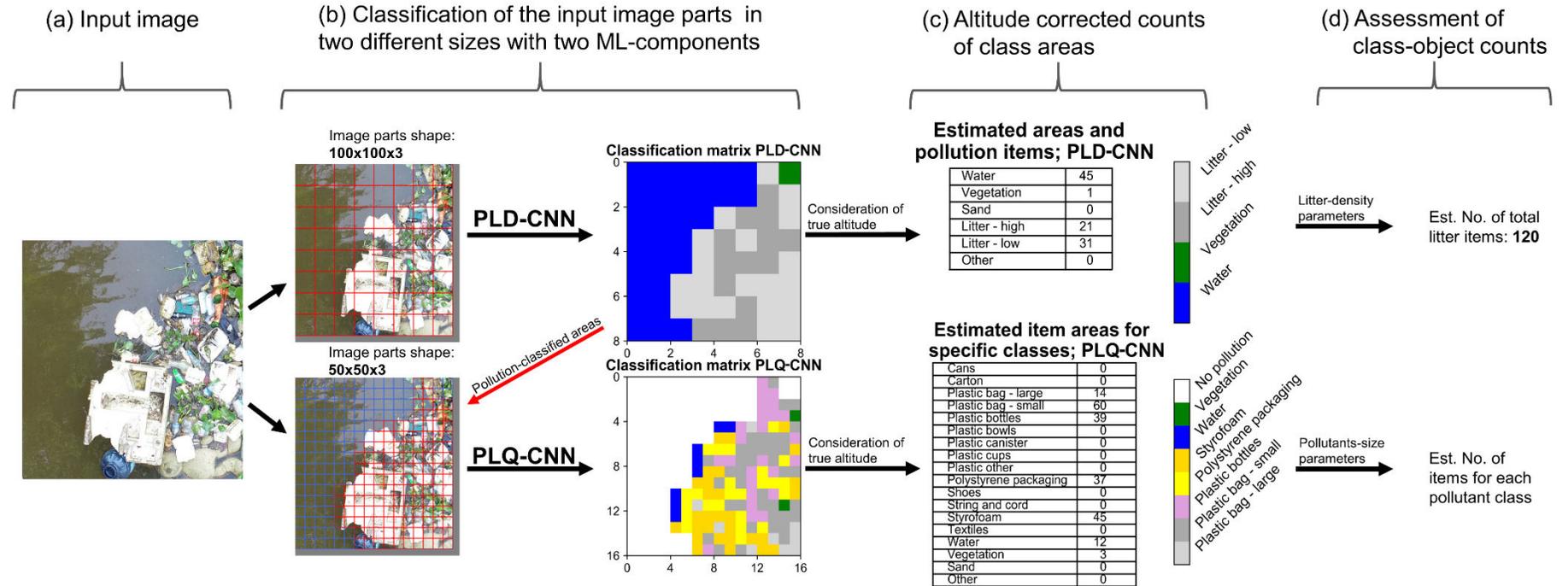


How accurate are the results?

# Image / video analysis with an AI based approach

## Plastic litter detection with machine learning using a two-step approach

- Assessment of plastic waste images (JPG, PNG, TIFF)
- Assessment of:
  - area covered
  - waste volume
  - types of waste
  - top 10 items



ENVIRONMENTAL RESEARCH LETTERS

LETTER • OPEN ACCESS

Machine learning for aquatic plastic litter detection, classification and quantification (APLASTIC-Q)

Mattis Wolf<sup>1,2</sup>, Katelijn van den Berg<sup>3</sup>, Shungudzemwoyo P. Garaba<sup>1,2</sup>, Nina Gnann<sup>1</sup>

Klaus Sattler<sup>3</sup>, Frederic Stahl<sup>1,4</sup> and Oliver Zielinski<sup>1,2</sup>

Published 16 November 2020 • © 2020 The Author(s). Published by IOP Publishing Ltd

Environmental Research Letters, Volume 15, Number 11

Citation Mattis Wolf et al 2020 Environ. Res. Lett. 15 114042

DOI 10.1088/1748-9326/abb01

10515 Total downloads



Turn on MathJax

Share this article



➔ Quantitative results and characterization of dominant pollution classes for plastic waste and other litter

# PLD CNN architecture and training details

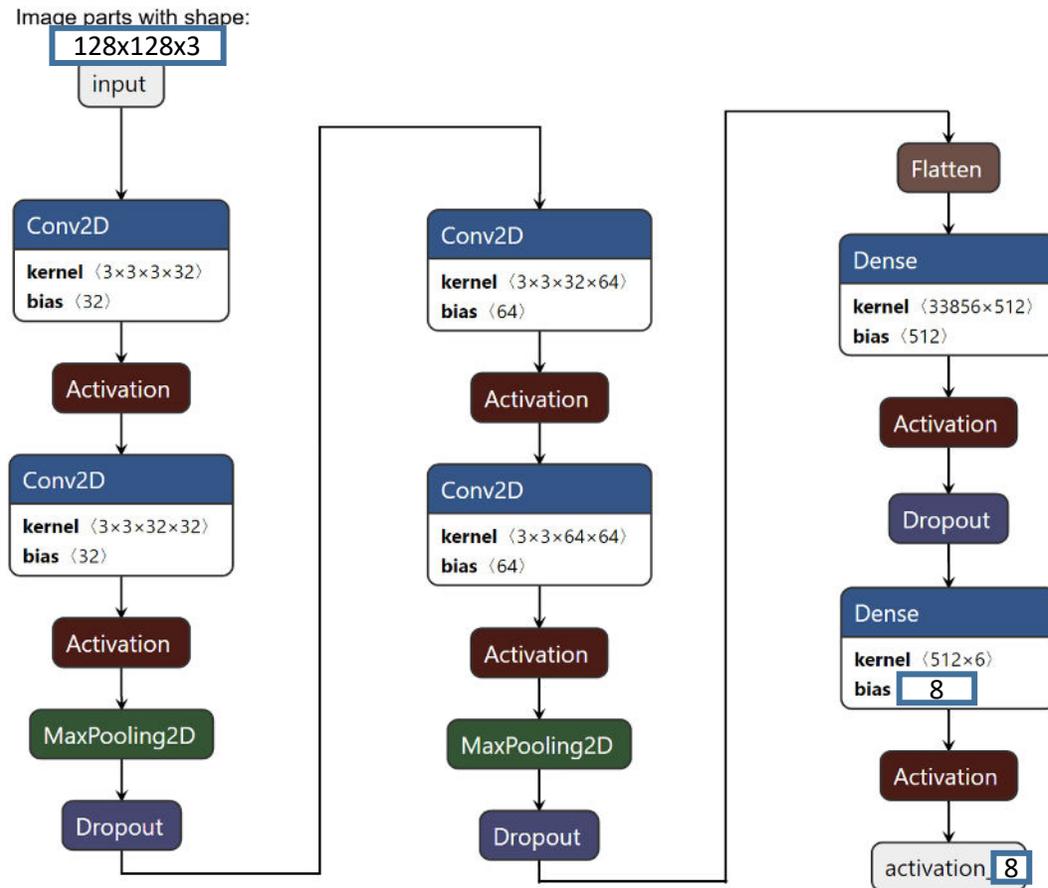
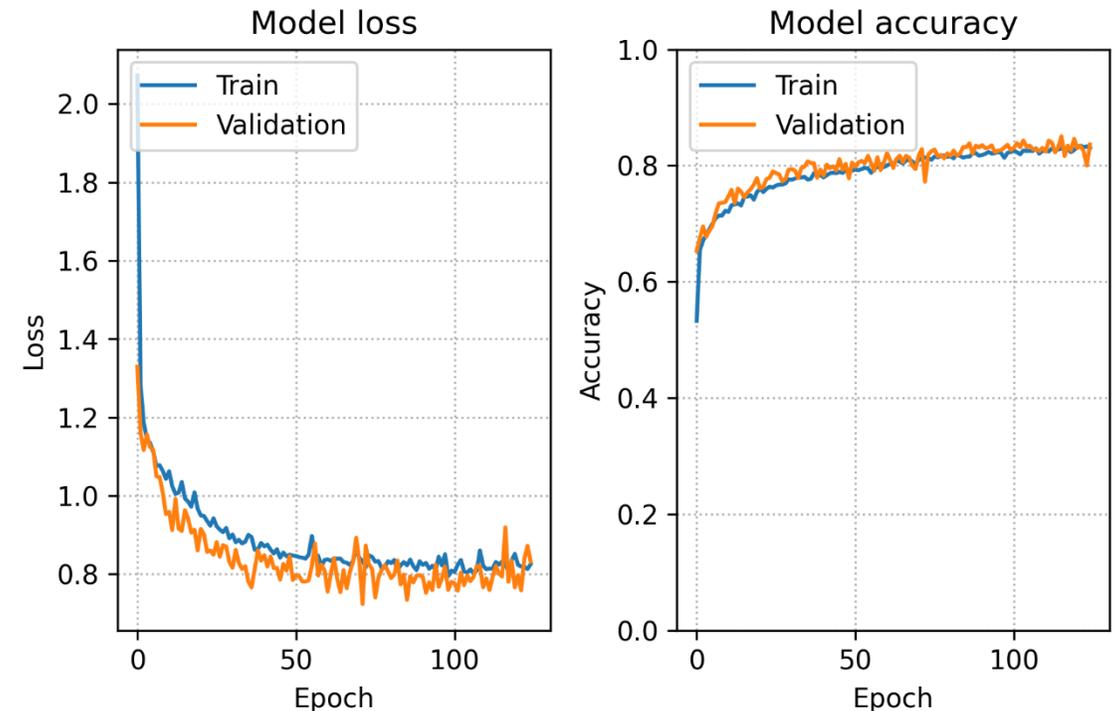
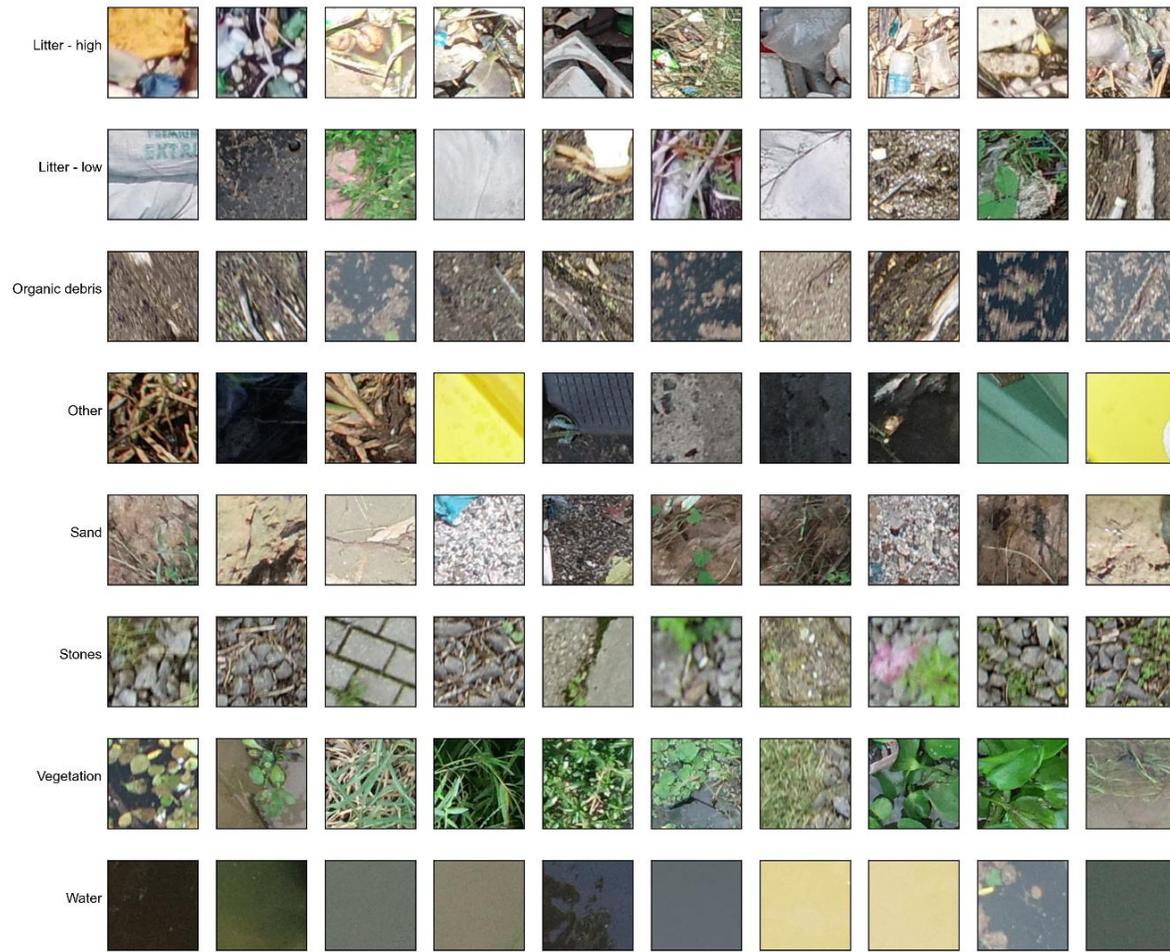


Figure 3. Architecture of the plastic litter detection convolutional neural network algorithm.

Adam(lr=0.001, beta\_1=0.9, beta\_2=0.999,  
amsgrad=False)  
Dense Layers with L2 regularization  
Data augmentation enabled during training



# 1<sup>st</sup> CNN: Plastic Litter Detection - dataset



True label \ Predicted label	Litter - high	Litter - low	Organic debris	Other	Sand	Stones	Vegetation	Water
Litter - high	822	89	1	7	24	0	3	0
Litter - low	96	294	166	33	56	2	49	13
Organic debris	2	28	762	0	3	1	3	2
Other	47	68	1	285	34	1	18	29
Sand	2	11	0	2	212	0	5	11
Stones	0	1	6	0	0	87	9	0
Vegetation	0	14	2	2	12	1	790	2
Water	0	1	8	7	1	0	19	1086

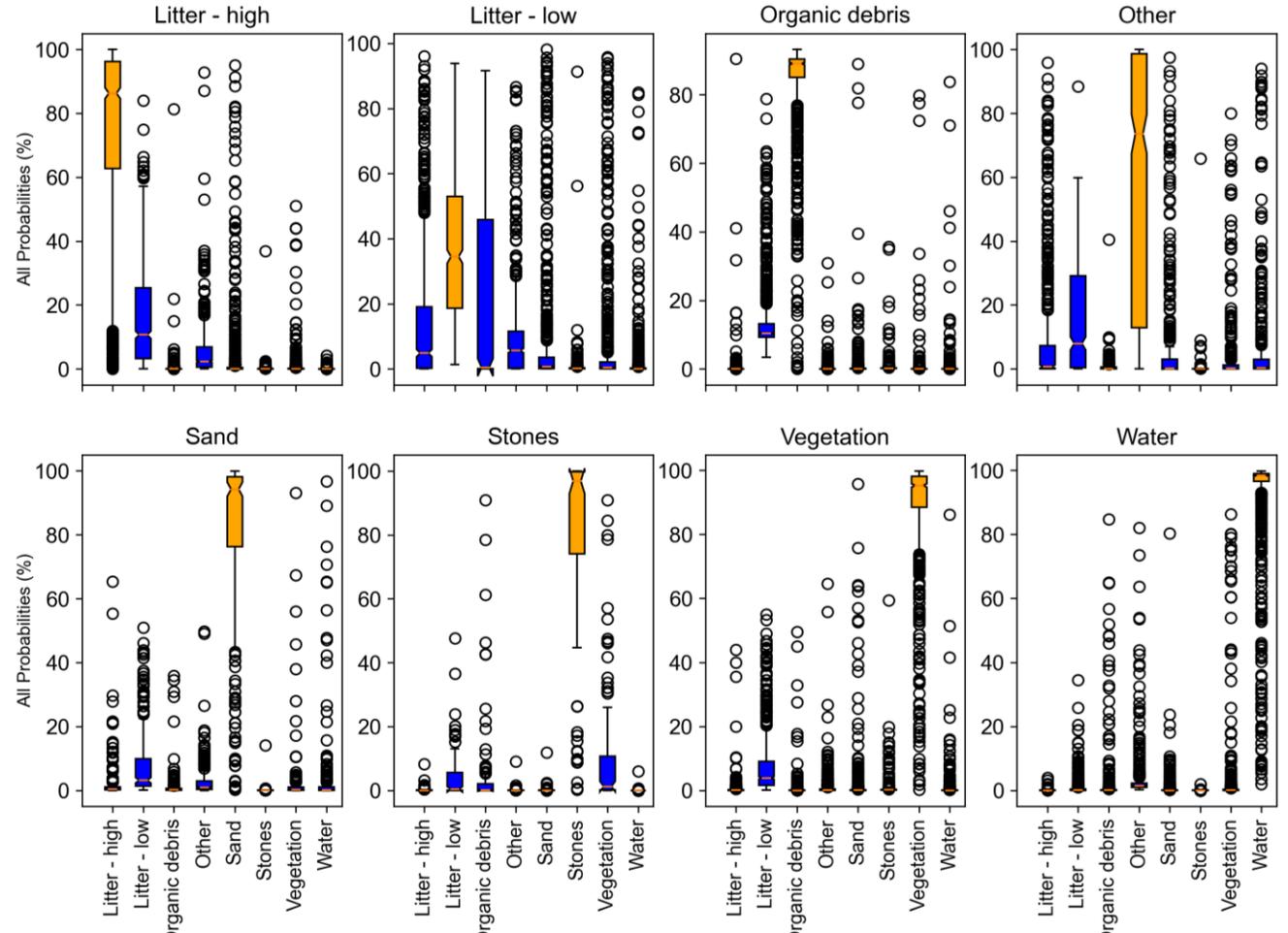
Example dataset from Cambodia project (enhanced dataset is planned to make OpenSource soon)



26.147 Training samples from multiple Southeastasian and European countries.  
Split: 70 / 15 / 15 (Training, Validation, Test)

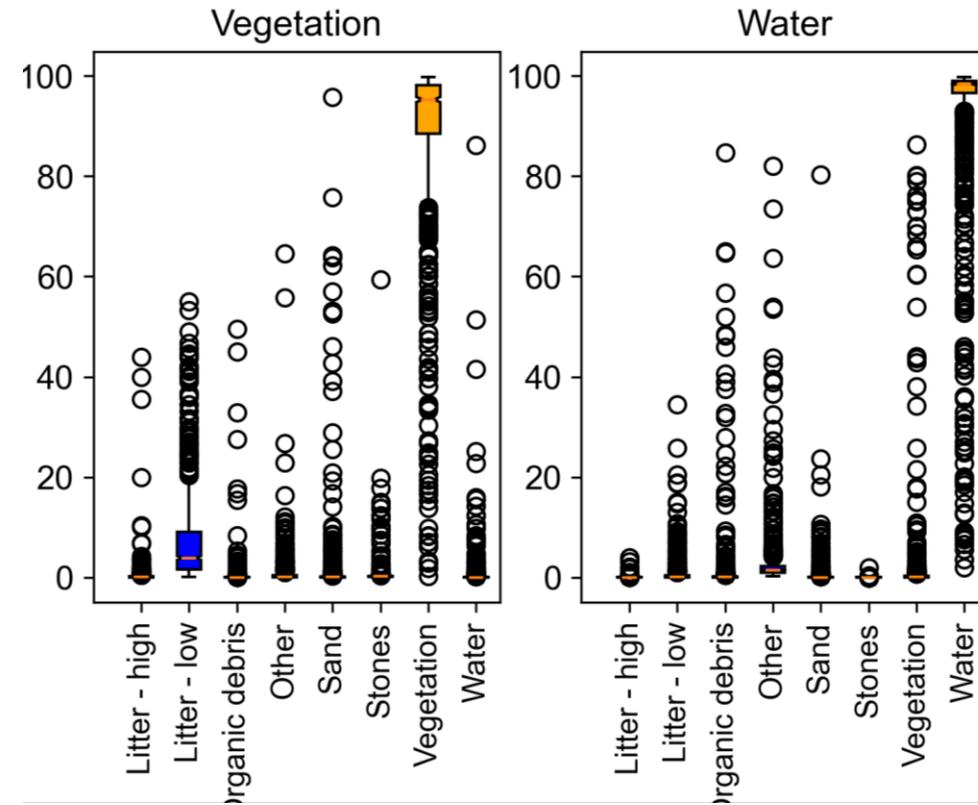
# CNN probability outputs for test samples

True label \ Predicted label	Litter - high	Litter - low	Organic debris	Other	Sand	Stones	Vegetation	Water
Litter - high	822	89	1	7	24	0	3	0
Litter - low	96	294	166	33	56	2	49	13
Organic debris	2	28	762	0	3	1	3	2
Other	47	68	1	285	34	1	18	29
Sand	2	11	0	2	212	0	5	11
Stones	0	1	6	0	0	87	9	0
Vegetation	0	14	2	2	12	1	790	2
Water	0	1	8	7	1	0	19	1086

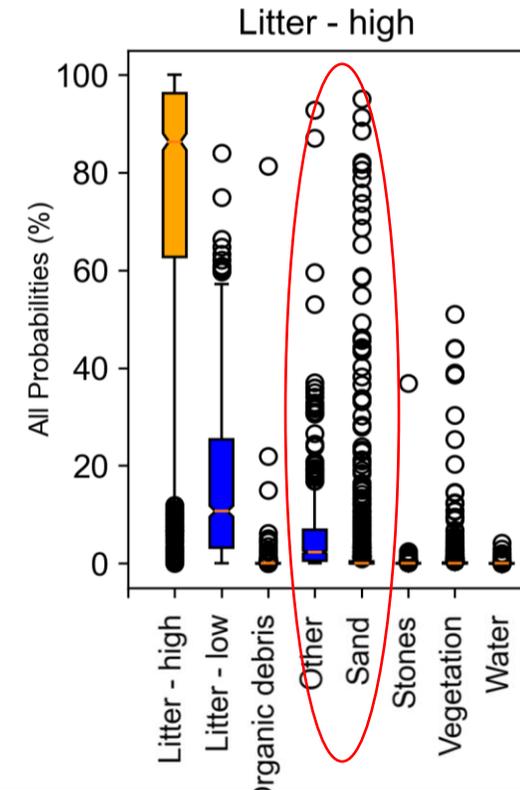
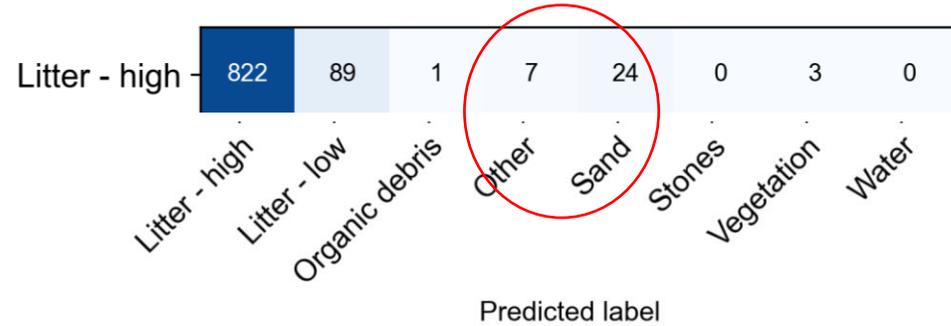


# CNN probability outputs for test samples

Vegetation	0	14	2	2	12	1	790	2
Water	0	1	8	7	1	0	19	1086
	Litter - high	Litter - low	Organic debris	Other	Sand	Stones	Vegetation	Water
	Predicted label							

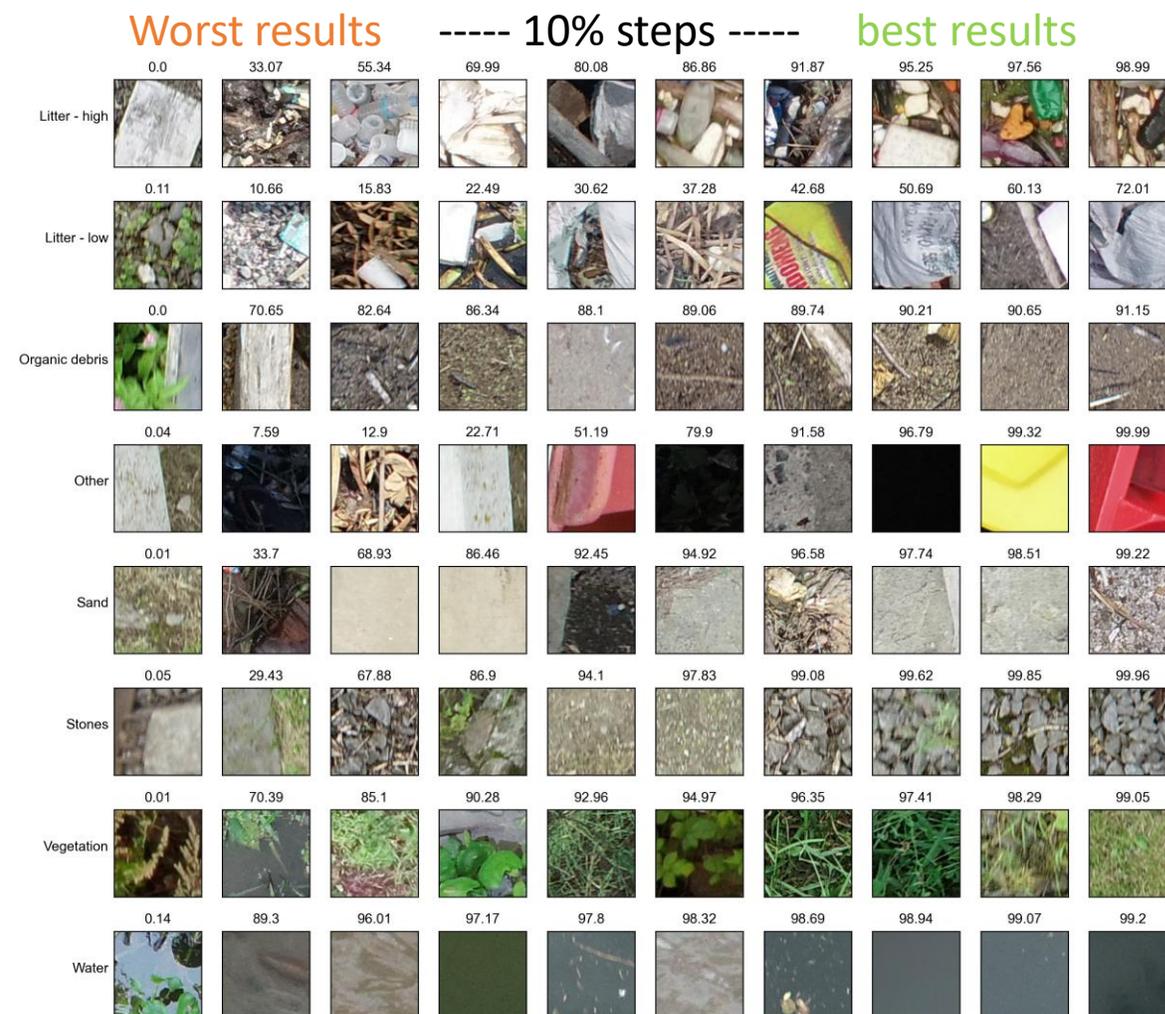


# CNN probability outputs for test samples

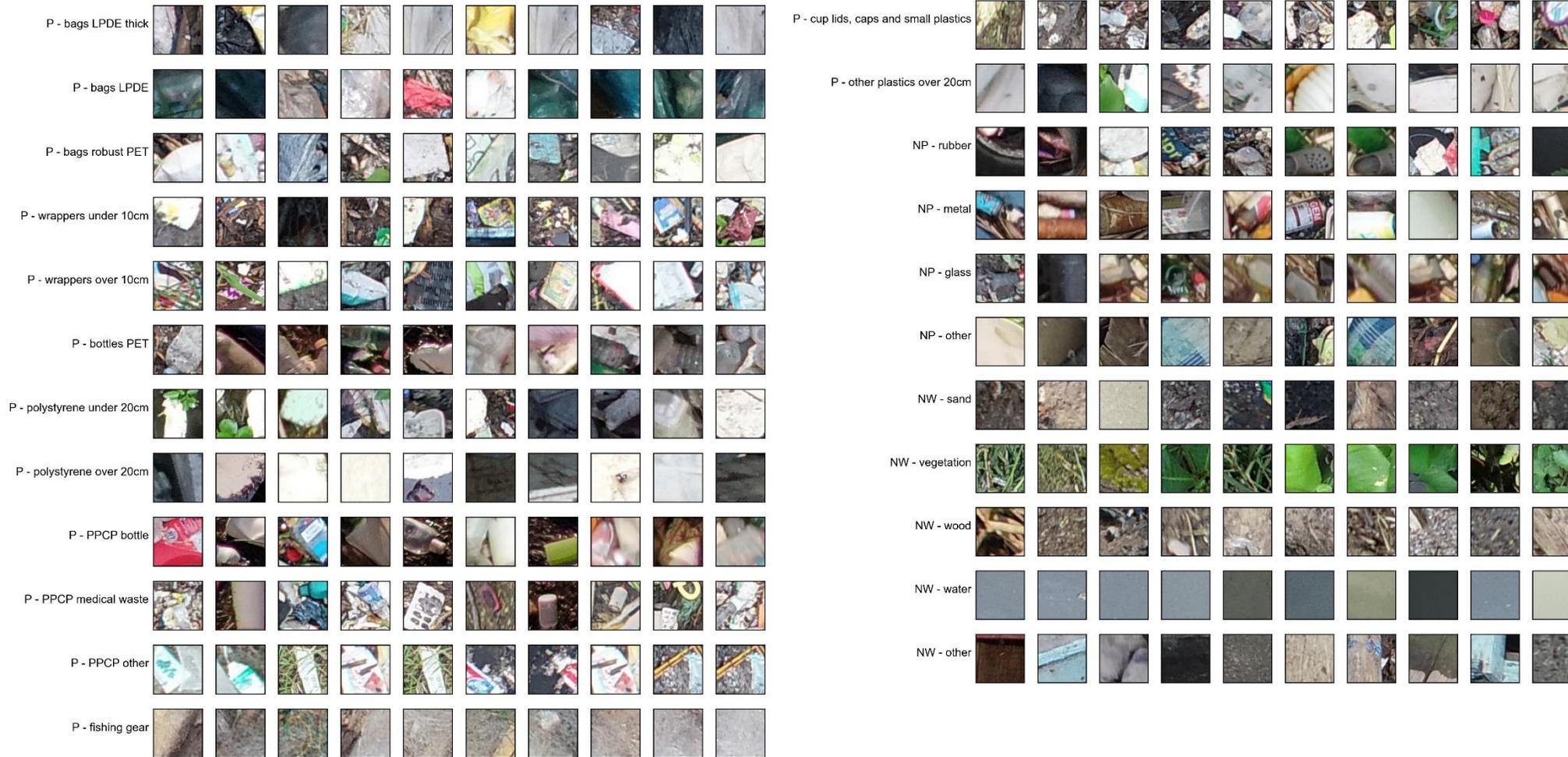


# Investigation of result samples

- What features occur (or do not occur), if the CNN is certain about classifications?
- What features occur (or do not occur), if the CNN is making mistakes?



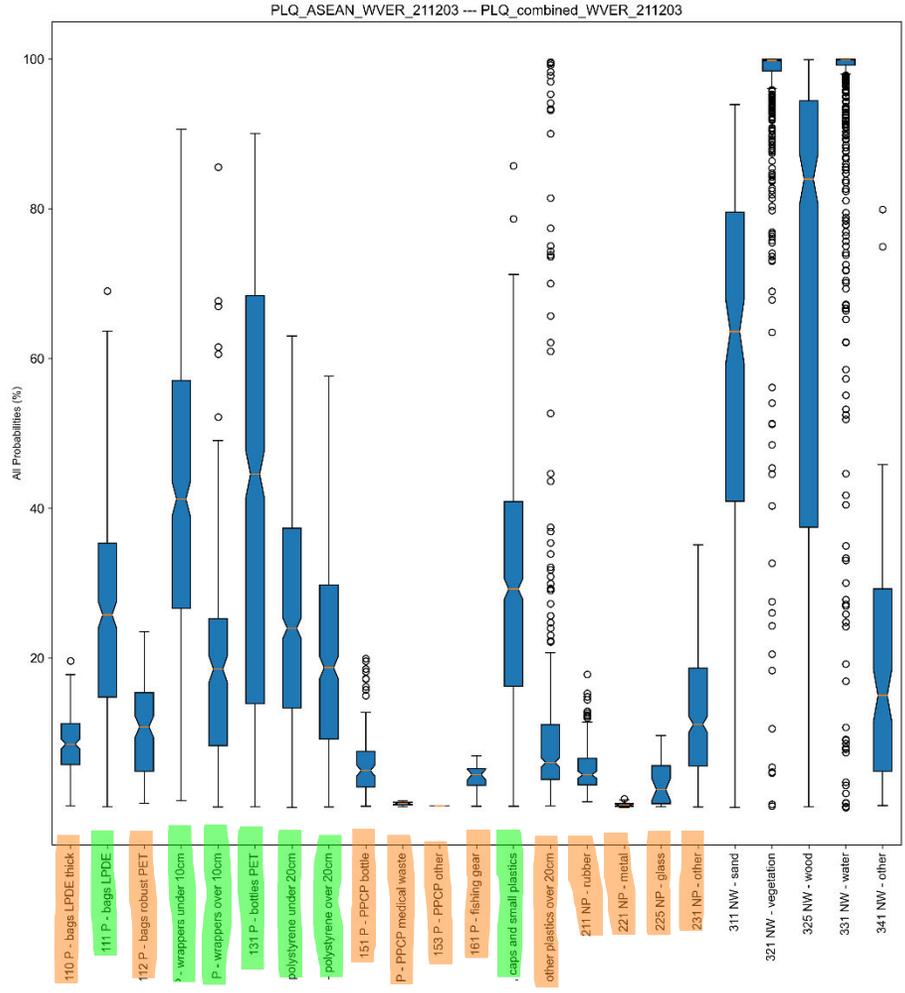
# 2<sup>nd</sup> CNN: Plastic Litter Quantifier - dataset



38.417 Training samples from multiple Southeastasian and European countries. Split: 70 / 15 / 15 (Training, Validation, Test)

# Recall probabilities for waste type classifications

True label	P - bags LPDE thick	P - bags LPDE	P - bags robust PET	P - wrappers under 10cm	P - wrappers over 10cm	P - bottles PET	P - polystyrene under 20cm	P - polystyrene over 20cm	P - PPCP bottle	P - PPCP medical waste	P - PPCP other	P - fishing gear	P - cup lids, caps and small plastics	P - other plastics over 20cm	NP - rubber	NP - metal	NP - glass	NP - other	NW - sand	NW - vegetation	NW - wood	NW - water	NW - other	
P - bags LPDE thick	74	0	6	3	13	14	7	0	0	0	0	0	18	2	0	0	0	0	21	4	5	6	3	0
P - bags LPDE	207	0	15	3	21	19	4	0	0	0	0	0	17	1	0	0	0	0	21	4	5	1	1	2
P - bags robust PET	81	0	10	2	1	11	12	0	0	0	0	0	9	0	0	0	0	0	2	3	1	0	0	2
P - wrappers under 10cm	26	0	292	15	0	2	0	0	0	0	0	0	62	1	0	0	0	0	4	3	4	0	2	0
P - wrappers over 10cm	40	0	115	30	5	6	2	0	0	0	0	0	16	0	0	0	0	0	3	0	3	1	0	1
P - bottles PET	133	0	16	1	468	51	0	0	0	0	0	0	38	0	0	0	0	0	12	2	8	8	1	2
P - polystyrene under 20cm	81	0	34	1	64	427	52	0	0	0	0	0	54	2	0	0	0	0	10	5	6	12	2	0
P - polystyrene over 20cm	34	3	7	0	12	158	170	0	0	0	0	0	15	8	0	0	0	0	21	34	5	5	13	2
P - PPCP bottle	2	0	1	0	60	21	0	0	0	0	0	0	9	0	0	0	0	0	2	0	0	1	0	0
P - PPCP medical waste	0	0	1	0	4	0	0	0	0	0	0	0	9	0	0	0	0	0	1	0	0	2	0	0
P - PPCP other	0	0	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
P - fishing gear	0	0	0	0	0	0	1	0	0	0	0	0	3	0	0	0	0	0	0	18	0	1	0	1
P - cup lids, caps and small plastics	38	0	183	3	67	30	5	0	0	0	0	0	383	6	0	0	0	0	10	10	22	39	5	1
P - other plastics over 20cm	62	0	16	0	19	55	82	0	0	0	0	0	26	40	0	0	0	0	7	4	4	6	11	3
NP - rubber	15	0	13	2	36	6	1	0	0	0	0	0	33	0	0	0	0	0	19	1	3	3	3	0
NP - metal	3	0	1	0	5	2	0	0	0	0	0	0	5	0	0	0	0	0	1	0	1	1	2	0
NP - glass	3	0	0	0	16	0	0	0	0	0	0	0	9	0	0	0	0	0	0	0	2	0	0	0
NP - other	64	0	10	0	11	22	10	0	0	0	0	0	55	1	0	0	0	0	80	44	8	37	12	12
NW - sand	0	0	1	0	2	0	1	0	0	0	0	0	8	0	0	0	0	0	3	168	0	11	2	4
NW - vegetation	2	0	0	0	3	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	796	8	0	0
NW - wood	1	0	0	0	25	11	1	0	0	0	0	0	28	0	0	0	0	0	23	37	17	548	0	5
NW - water	1	1	0	0	0	0	4	0	0	0	0	0	0	2	0	0	0	0	5	1	0	1	770	2
NW - other	18	0	0	0	15	2	0	0	0	0	0	0	1	0	0	0	0	0	12	45	1	8	3	14



# Waste type classifications: worst to best

P - bags LPDE thick	0.08	3.65	5.22	6.35	7.75	8.7	9.86	11.05	11.89	12.96
P - bags LPDE	0.0	7.19	12.53	17.66	21.43	25.04	28.36	32.17	37.35	46.48
P - bags robust PET	0.05	2.53	4.13	5.87	7.56	9.32	11.15	12.94	14.96	17.51
P - wrappers under 10cm	0.03	13.88	23.54	30.47	37.55	43.7	49.25	54.7	60.93	68.21
P - wrappers over 10cm	0.07	4.83	7.68	11.03	14.09	16.96	20.25	23.83	29.13	38.19
P - bottles PET	0.03	8.68	12.89	19.09	30.7	47.15	59.46	66.7	72.19	76.71
P - polystyrene under 20cm	0.03	5.34	10.56	15.7	20.3	24.25	29.05	34.61	40.38	47.44
P - polystyrene over 20cm	0.0	3.53	7.65	11.97	15.55	19.34	23.2	27.28	31.47	37.66
P - PPCP bottle	0.0	0.78	2.0	3.15	4.18	4.88	5.93	7.53	9.55	13.16
P - PPCP medical waste	0.03	0.14	0.31	0.42	0.47	0.53	0.57	0.64	0.73	0.78
P - PPCP other	0.01	0.15	0.16	0.16	0.18	0.19	0.23	0.25	0.28	0.29
P - fishing gear	0.1	0.99	2.07	3.07	3.91	4.41	4.97	5.44	5.62	6.15

P - cup lids, caps and small plastics	0.04	7.71	13.53	19.39	24.52	29.01	33.37	37.47	42.32	49.71
P - other plastics over 20cm	0.01	2.1	3.17	4.0	5.01	6.15	6.78	9.74	16.5	31.52
NP - rubber	0.19	1.98	2.84	3.41	3.89	4.55	5.43	6.3	7.27	9.42
NP - metal	0.0	0.14	0.27	0.32	0.38	0.47	0.54	0.61	0.81	0.93
NP - glass	0.05	0.29	0.41	1.12	2.01	2.87	3.75	4.98	5.61	7.11
NP - other	0.02	3.23	5.01	7.08	9.21	11.39	13.81	16.79	20.14	24.44
NW - sand	0.04	20.46	39.17	50.16	56.64	63.9	69.87	74.69	80.02	84.74
NW - vegetation	0.16	93.13	97.6	98.87	99.43	99.73	99.88	99.95	99.98	100.0
NW - wood	0.11	9.73	28.86	52.84	68.88	81.84	88.76	92.59	95.1	96.92
NW - water	0.01	90.49	98.69	99.56	99.78	99.87	99.93	99.96	99.98	99.99
NW - other	0.0	2.15	3.51	7.16	11.34	18.02	24.53	29.09	34.6	39.68

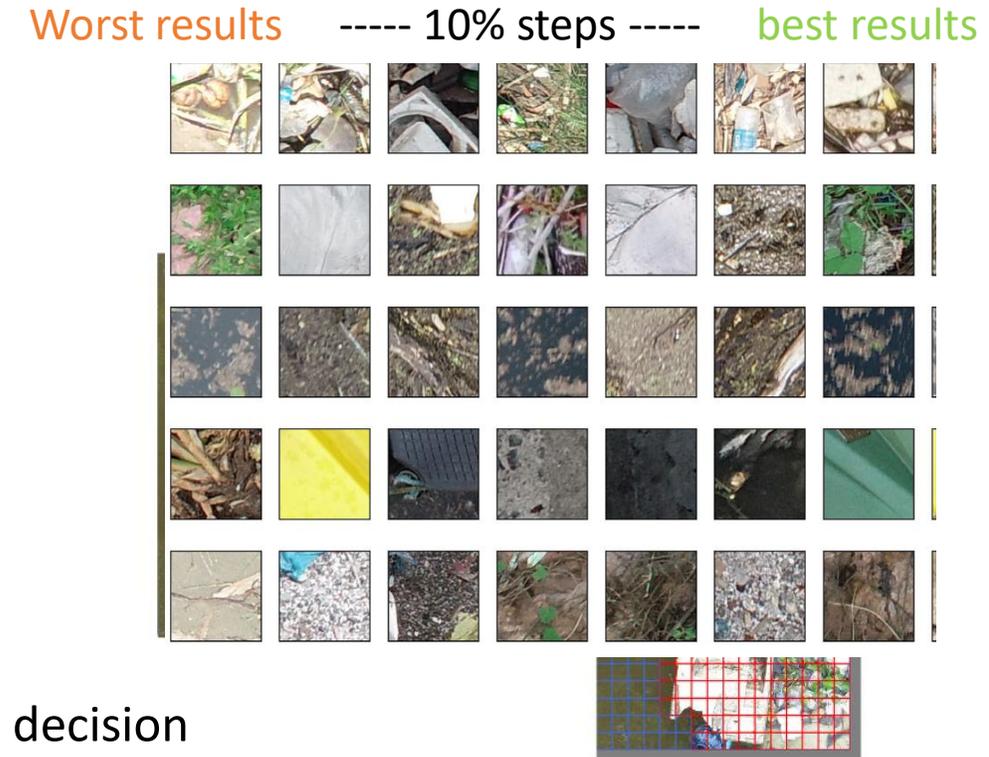
Which waste types can the CNN detect?

How certain are classifications?

-> info needs to be provided to give context for waste assessment

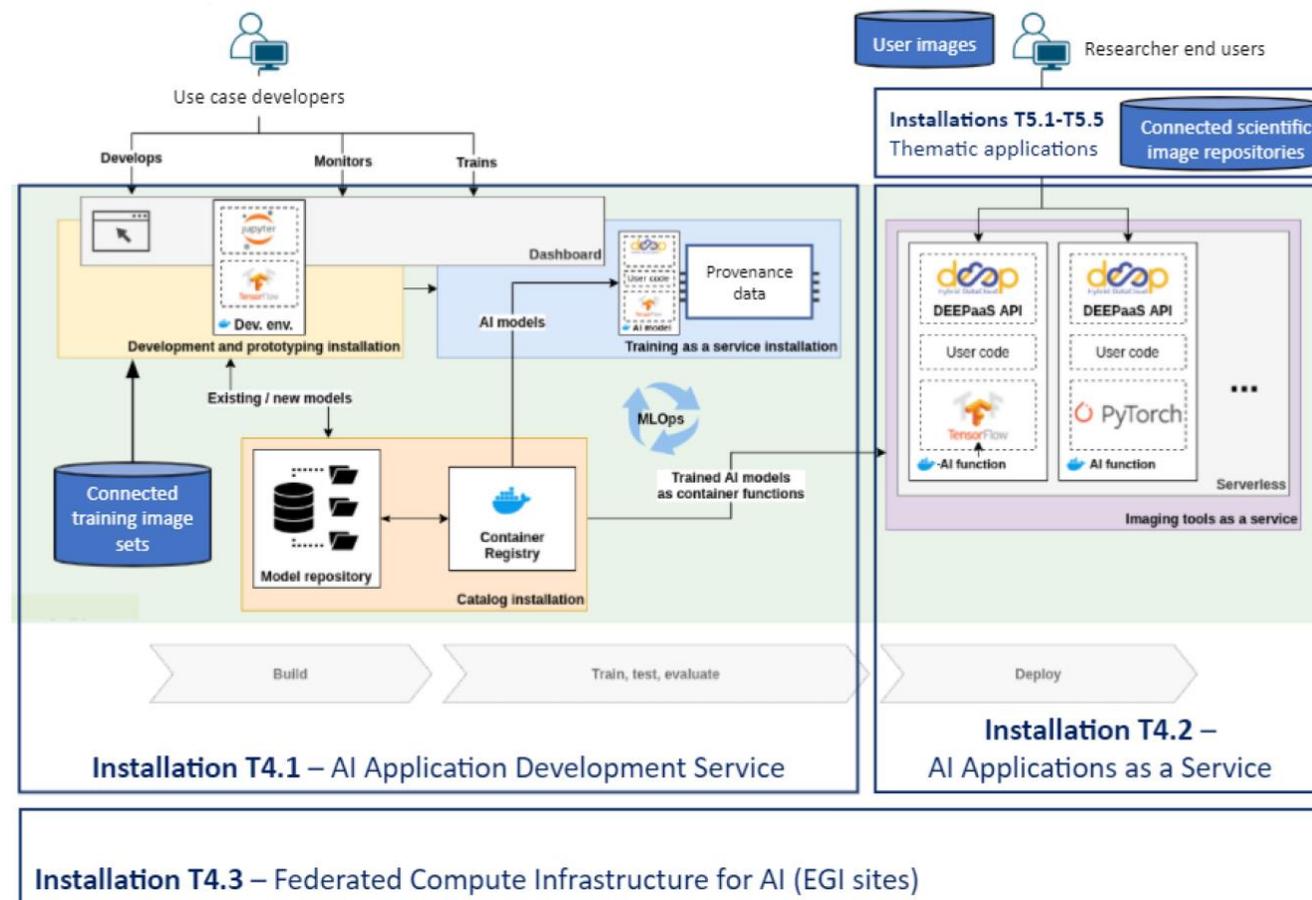
# Next steps

- Use of well known explanation methods like
  - Local Interpretable Model-agnostic Explanations (LIME)
  - SHapley Additive exPlanations (SHAP)
- Problems:
  - APLASTIC-Q works on small tiles of the image
  - Explanations also must work on tiles
  - Usefulness questioned for larger images
- Approach:
  - Use methods on the training samples
  - Show users what part of the image the algorithms used for decision



# iMagine - AI as a web service: APLASTIC-Q as application

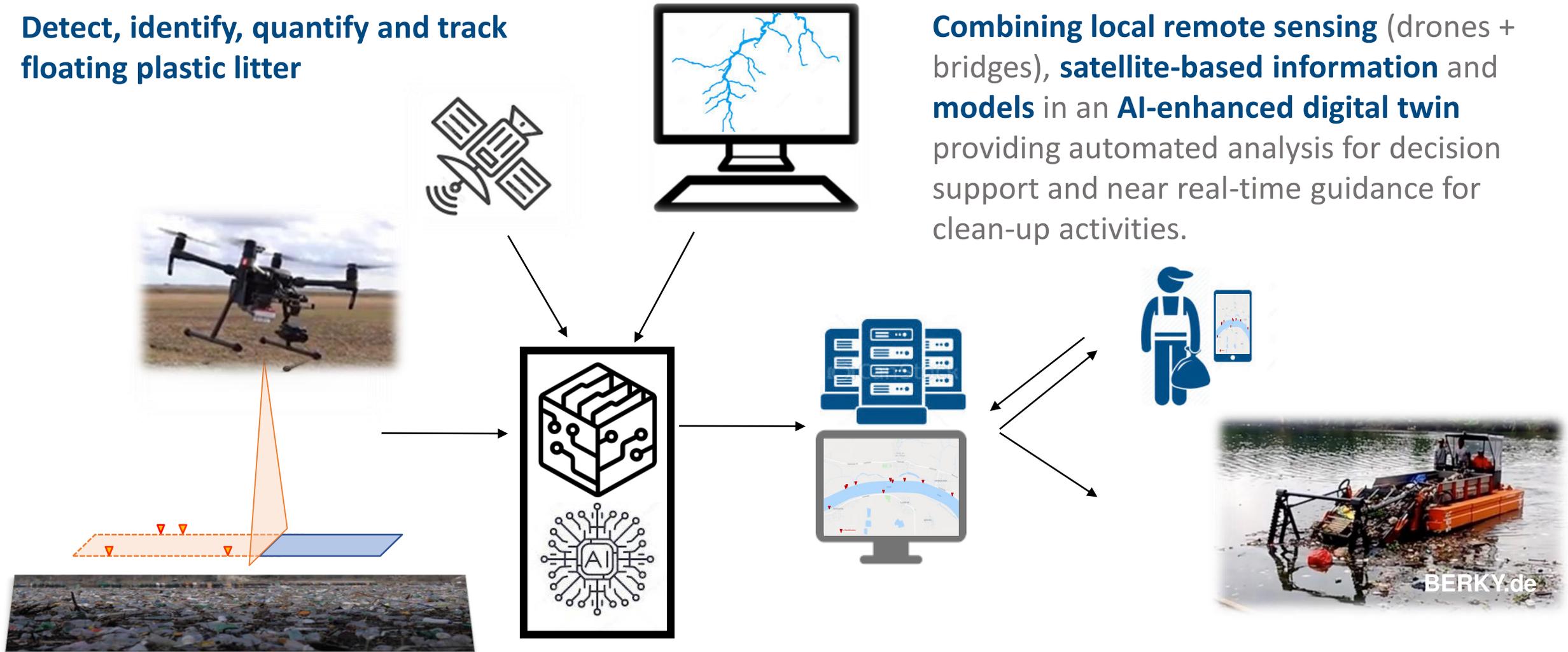
- Enable Natural Scientists to use AI Techniques
- Plastic Waste Analysis as Use Case
- Offering pre-trained AI-Modules
- Allow Training with User Images
- Free at point of use
  - image datasets
  - image analysis tools
- **Enable better and more efficient processing and analysis of imaging data**
- Accelerating scientific insights



# Overall vision: From perception to action

**Detect, identify, quantify and track floating plastic litter**

**Combining local remote sensing (drones + bridges), satellite-based information and models in an AI-enhanced digital twin** providing automated analysis for decision support and near real-time guidance for clean-up activities.



# Assistance System for Nautical Officers



# Assistance System for Nautical Officers

90 % of world trade carried over the oceans

reducing costs of operation is mandatory

- reduce staff onboard
- faster operations
- larger ships
- force automatisation of processes

increasing mental load of staff

- dangerous situations
- situational awareness errors account for almost every third accident (Grech et al. 2002)



Instagram/fallenhearts17

# Assistance System for Nautical Officers

- Autonomous ships could be a solution
- Many different directions of research in this field
  - (small) prototypes unmanned surface vehicles
  - autonomous ferries (NTNU)
- Main reasons for automatisisation
  - Reducing risks
  - Saving energy
  - Reducing emissions
  - Reducing costs
  - Protecting humans



- Current rules and standards are not made for autonomous ships
  - International Regulations for Preventing Collisions at Sea (COLREGS) (Ventura 2005)
- Regularisation is done by international and national organisations (IMO, DNVGL, etc.)
- IMO defined four levels of autonomy for sea going vessels
- Autonomous systems must ensure to follow the COLREGS (DNVGL 2018)
  - Need of certification

## Autonomy level 1

- Vessel with automated processes and decision support systems
- Crew on board

## Autonomy level 2

- Remotely operated vessel
- Crew onboard

## Autonomy level 3

- Remotely operated vessel
- No crew onboard

## Autonomy level 4

- fully autonomous vessel
- No crew onboard

# Assistance System for Nautical Officers



maritimeroboti



norwegianscitechnews

IBM and ProMare



## Autonomy level 1

- Vessel with automated processes and decision support systems
- Crew on board

## Autonomy level 2

- Remotely operated vessel
- Crew onboard

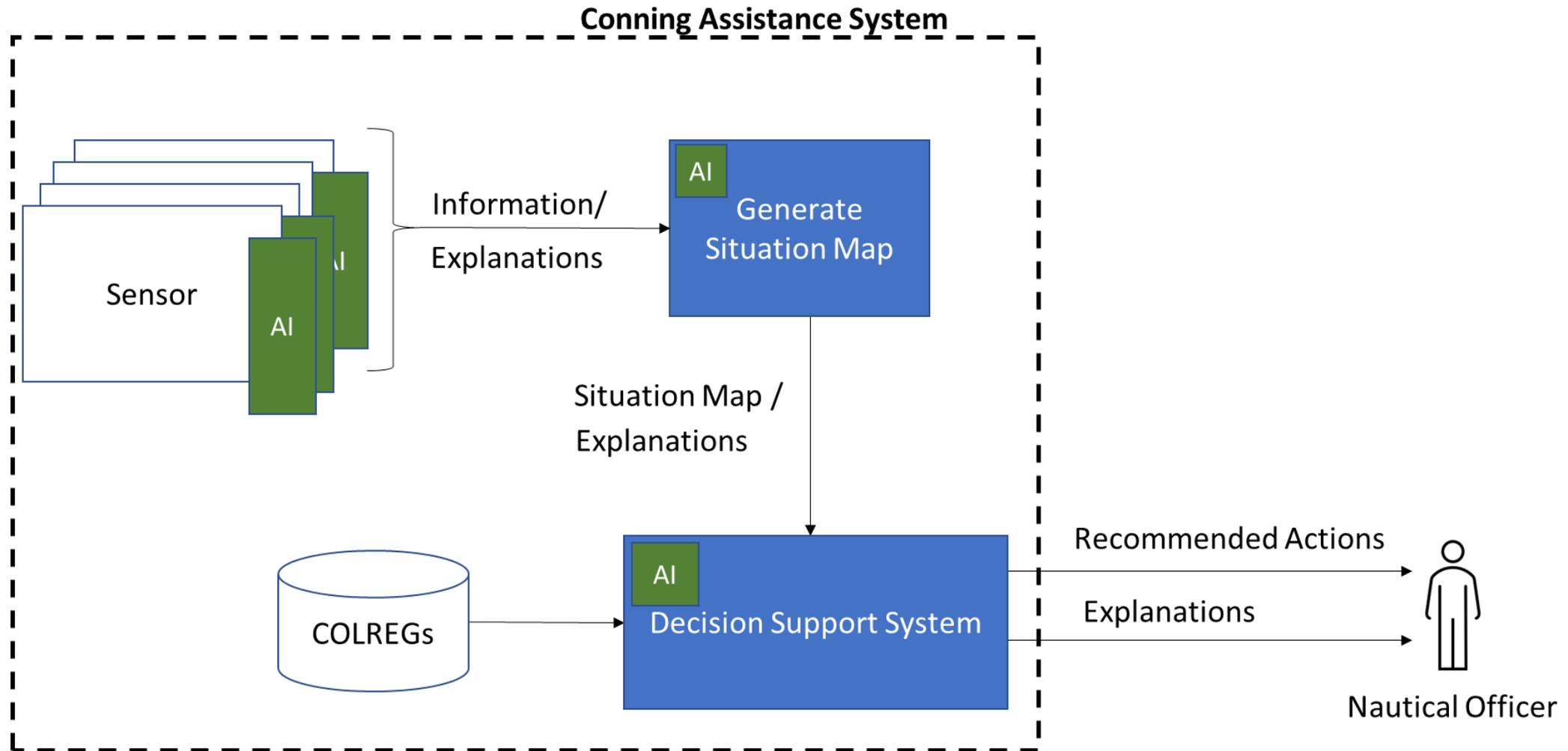
## Autonomy level 3

- Remotely operated vessel
- No crew onboard

## Autonomy level 4

- fully autonomous vessel
- No crew onboard

# Assistance System for Nautical Officers



# Assistance System for Nautical Officers

- Development of explainable assistance system for nautical officers
- Provide COLREG conform recommended actions
- Deliver explanations for decisions
- First step towards autonomous ships
- Planned start: Summer 2023



# Conclusions

## APLASTIC-Q

- Explanations helped stakeholders to gain confidence in AI solutions
- Explanations helped to identify worse working classes in plastic waste quantification
- Potentially further use of model agnostic methods to improve explainability

## Assistance System for Nautical Officers

- Long way towards autonomous ships
- Research is needed in this area
- XAI could be a tool to enable certification of autonomous ships in the future

Thanks  
for your  
attention!



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